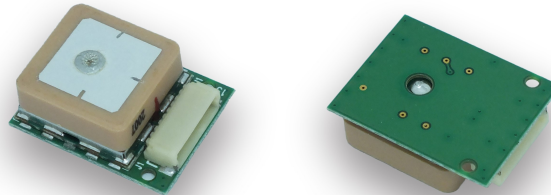


Product name	Description	Version
LS2003D-G	Standalone multiple GNSS smart antenna module	1.5



21 x 17 x 7.2 mm

1 Introduction

LS2003D-G is a complete standalone GNSS smart antenna module, including embedded patch antenna and GNSS receiver circuits. The module can simultaneously acquire and track multiple satellite constellations that include GPS, GLONASS, GALILEO, QZSS and SBAS. It features low power and small form factor. Besides, it can provide you with superior sensitivity and performance even in urban canyon and dense foliage environment.

This module supports hybrid ephemeris prediction to achieve faster cold start. One is self-generated ephemeris prediction (called EASY) that is no need of both network assistance and host CPU's intervention. This is valid for up to 3 days and updates automatically from time to time when GNSS module is powered on and satellites are available. The other is server-generated ephemeris prediction (called EPO) that gets from an internet server. This is valid for up to 14 days. Both ephemeris predictions are stored in the on-board flash memory and perform a cold start time less than 15 seconds.

It is easy to install without both RF connector and coaxial cable that are needed in a separated GNSS active antenna. In other words, reduce the cost and size. Also, speed up the time to market by eliminating R&D efforts on RF matching and stability between separated GNSS antenna and module. Furthermore, it can be directly powered by a lithium battery without any external voltage regulars. Therefore, LS2003D-G of miniature size and brilliant performance is the best choice to be integrated into your slim devices.

2 Features

- MediaTek high sensitivity solution
- Support GPS, GLONASS, GALILEO and QZSS
- Capable of SBAS (WAAS, EGNOS, MSAS, GAGAN)
- Support 99-channel GNSS
- Ultra low power consumption
- Fast TTFF at low signal level
- Built-in 12 multi-tone active interference canceller
- Free hybrid AGPS to achieve faster cold start
- Built-in data logger
- Built-in DC/DC converter to save power
- Allow direct connection with the lithium battery
- Up to 10 Hz update rate

- ±11ns high accuracy time pulse (1PPS)
- Indoor and outdoor multi-path detection and compensation
- RoHS compliant

3 Application

- Personal positioning and navigation
- Automotive navigation
- Marine navigation
- Weather balloon

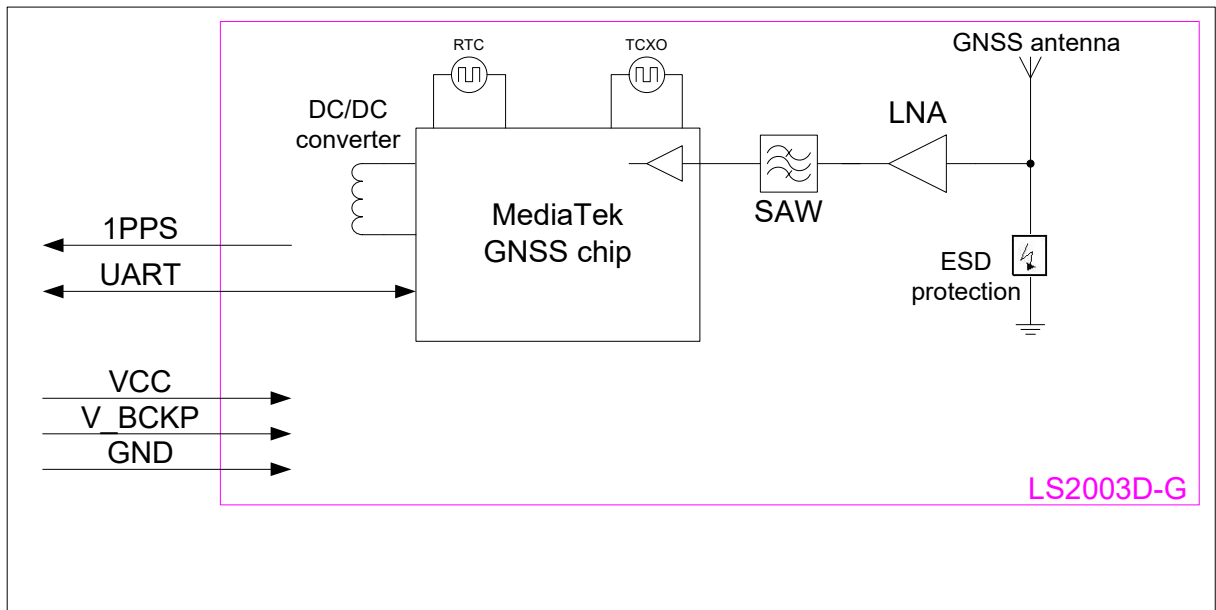


Fig 3-1 System block diagram of LS2003D-G

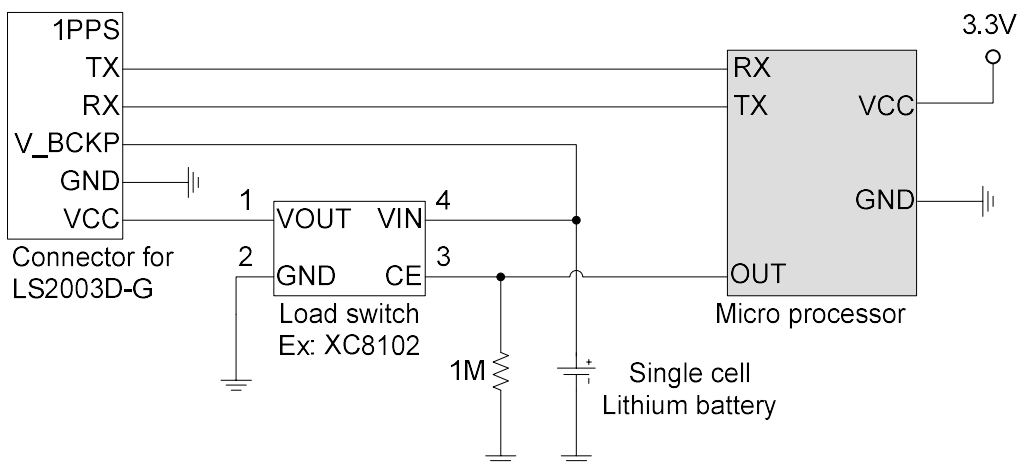


Fig 3-2 Typical application circuit that directly use lithium battery to save power.

4 GNSS receiver and antenna

4.1 GNSS receiver

Chip	MediaTek MT3333	
Frequency	GPS, GALILEO ⁽¹⁾ , QZSS: L1 1575.42MHz, C/A code GLONASS: L1 1598.0625MHz ~ 1605.375MHz, C/A code	
Channels	Support 99 channels (33 Tracking, 99 Acquisition)	
Update rate	1Hz default, up to 10Hz	
Acquisition Time	Hot start (Open Sky)	1s (typical)
	Cold Start (Open Sky)	34s (typical) without AGPS
		< 15s (typical) with AGPS (hybrid ephemeris prediction)
Position Accuracy	Autonomous	2.5m CEP
	SBAS	2.5m (depends on accuracy of correction data)
Datum	WGS-84 (default)	
Max. Altitude	< 18,000 m, up to 50,000m by request	
Max. Velocity	< 515 m/s	
Protocol	NMEA 0183 ver 4.00 ⁽²⁾	9600 bps ⁽³⁾ , 8 data bits, no parity, 1 stop bits 1Hz: GGA, GLL, GSA, GSV, RMC, VTG

Note (1): LS2003D-G module is default configured for concurrent GPS, GLONASS, QZSS and SBAS reception. Please contact us for different default configuration, such as concurrent GPS, GLONASS, GALILEO, QZSS and SBAS.

Note (2): The default NMEA version is 4.00 and it also can configure to 4.10. If customers want to the product to support 4.10 please contact us in advance.

Note (3): Both baud rate and output message rate are configurable.

4.2 GNSS antenna

Antenna type	Patch antenna
Frequency Range	1575.42MHz ± 1.023MHz ⁽¹⁾ 1598MHz ~ 1606MHz ⁽¹⁾
Gain	0.5 dBic Typ. @zenith ⁽¹⁾

Note 1: This value is measured with the evaluation board and must be fine tuned when installed into your device. Please contact LOCOSYS for your antenna tuning.

5 Software interface

5.1 NMEA output message

Table 5.1-1 NMEA output message

NMEA record	Description
GGA	Global positioning system fixed data
GLL	Geographic position - latitude/longitude
GSA	GNSS DOP and active satellites
GSV	GNSS satellites in view
RMC	Recommended minimum specific GPS data
VTG	Course over ground and ground speed

● GGA--- Global Positioning System Fixed Data

Table 5.1-2 contains the values for the following example:

\$GNGGA,183015.000,2503.7123,N,12138.7446,E,2,16,0.68,123.2,M,15.3,M,,*78

Table 5.1-2 GGA Data Format

Name	Example	Units	Description
Message ID	\$GNGGA		GGA protocol header
UTC Time	183015.000		hhmmss.sss
Latitude	2503.7123		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12138.7446		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Position Fix Indicator	2		See Table 5.1-3
Satellites Used	16		Range 0 to 33
HDOP	0.68		Horizontal Dilution of Precision
MSL Altitude	123.2	meters	
Units	M	meters	
Geoid Separation	15.3	meters	
Units	M	meters	
Age of Diff. Corr.		second	Null fields when DGPS is not used
Diff. Ref. Station ID			
Checksum	*78		
<CR> <LF>			End of message termination

Table 5.1-3 Position Fix Indicators

Value	Description
0	Fix not available or invalid
1	GPS SPS Mode, fix valid

2	Differential GPS, SPS Mode, fix valid
3-5	Not supported
6	Dead Reckoning Mode, fix valid

● GLL--- Geographic Position – Latitude/Longitude

Table 5.1-4 contains the values for the following example:

\$GNGLL,2503.7135,N,12138.7448,E,055757.000,A,D*45

Table 5.1-4 GLL Data Format

Name	Example	Units	Description
Message ID	\$GNGLL		GLL protocol header
Latitude	2503.7135		ddmm.mmmm
N/S indicator	N		N=north or S=south
Longitude	12138.7448		dddmm.mmmm
E/W indicator	E		E=east or W=west
UTC Time	055757.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Mode	D		N = No position fix A = Autonomous GNSS fix D = Differential GNSS fix R = RTK fixed F = RTK float E = Estimated/Dead reckoning fix
Checksum	*45		
<CR> <LF>			End of message termination

● GSA---GNSS DOP and Active Satellites

Table 5.1-5 contains the values for the following example:

NMEA V4.0

\$GPGSA,A,3,193,19,06,05,02,17,09,12,13,195,,1.23,0.92,0.81*01

\$GLGSA,A,3,69,,,,,,,,,1.23,0.92,0.81*13

\$GAGSA,A,3,,,,,,,,,1.23,0.92,0.81*11

NMEA V4.10

\$GNRSA,A,3,02,06,17,19,09,05,28,193,195,,1.34,1.02,0.87,1*01

\$GNRSA,A,3,69,,,,,,,,,1.34,1.02,0.87,2*07

\$GNRSA,A,3,,,,,,,,,1.34,1.02,0.87,3*09

Table 5.1-5 GSA Data Format

Name	Example	Units	Description
------	---------	-------	-------------

Message ID	\$GNGSA		GSA protocol header, GP=GPS/QZSS, GL=GLONASS, GA=GALILEO, BD=BEIDOU (GN for NMEA Ver 4.10)
Mode 1	A		See Table 5.1-6
Mode 2	3		See Table 5.1-7
ID of satellite used	02		Sv on Channel 1
ID of satellite used	06		Sv on Channel 2
....		
ID of satellite used			Sv on Channel N
PDOP	1.34		Position Dilution of Precision
HDOP	1.02		Horizontal Dilution of Precision
VDOP	0.87		Vertical Dilution of Precision
System ID	1		1: GPS, 2:GLONASS, 3:GALILEO, 4:BEIDOU (NMEA Ver 4.10 support only)
Checksum	*01		
<CR> <LF>			End of message termination

Table 5.1-6 Mode 1

Value	Description
M	Manual- forced to operate in 2D or 3D mode
A	Automatic-allowed to automatically switch 2D/3D

Table 5.1-7 Mode 2

Value	Description
1	Fix not available
2	2D
3	3D

● GSV---GNSS Satellites in View

Table 5.1-8 contains the values for the following example:

\$GPGSV,3,1,11,18,67,344,48,09,55,031,50,42,54,142,40,193,47,174,45,0*51

\$GPGSV,3,2,11,21,44,219,46,27,39,035,48,12,34,131,44,15,30,057,46,0*6A

\$GPGSV,3,3,11,22,27,319,47,14,22,285,42,25,19,171,40,0*58

\$GLGSV,2,1,07,76,71,201,44,65,57,041,40,75,48,028,39,72,27,108,39,1*75

\$GLGSV,2,2,07,66,25,333,43,77,17,207,37,81,02,280,29,1*41

\$GAGSV,2,1,05,01,83,026,35,26,53,024,35,21,38,134,30,12,16,233,21,0*70

\$GAGSV,2,2,05,18,,,30,0*7B

Table 5.1-8 GSV Data Format

Name	Example	Units	Description
------	---------	-------	-------------

Message ID	\$GPGSV		GSV protocol header GP=GPS/QZSS, GL=GLONASS, GA=GALILEO, BD=BEIDOU
Total number of messages ⁽¹⁾	3		Range 1 to 6
Message number ⁽¹⁾	1		Range 1 to 6
Satellites in view	11		
Satellite ID ⁽²⁾	18		Channel 1 (Range 01 to 196)
Elevation	67	degrees	Channel 1 (Range 00 to 90)
Azimuth	344	degrees	Channel 1 (Range 000 to 359)
SNR (C/No)	48	dB-Hz	Channel 1 (Range 00 to 99, null when not tracking)
Satellite ID	09		Channel 4 (Range 01 to 196)
Elevation	55	degrees	Channel 4 (Range 00 to 90)
Azimuth	031	degrees	Channel 4 (Range 000 to 359)
SNR (C/No)	50	dB-Hz	Channel 4 (Range 00 to 99, null when not tracking)
	...		
Signal ID	0		GPS/QZSS: All signal=0, GLONASS: All signal=0, G1 C/A=1 GALILEO: All signal=0, BEIDOU: All signal=0 (NMEA Ver 4.10 support only)
Checksum	*51		
<CR> <LF>			End of message termination

Note (1): Depending on the number of satellites tracked multiple messages of GSV data may be required.

Note (2): GPS ID: 01~32, SBAS ID: 33~64, QZSS ID: 193~196, BEIDOU ID: 01~32, GALILEO ID: 01~32

● RMC---Recommended Minimum Specific GNSS Data

Table 5.1-9 contains the values for the following example:

\$GNRMC,183015.000,A,2503.7123,N,12138.7446,E,0.01,34.92,270812,,,D,V*39

Table 5.1-9 RMC Data Format

Name	Example	Units	Description
Message ID	\$GPRMC		RMC protocol header
UTC Time	183015.000		hhmmss.sss
Status	A		A=data valid or V=data not valid
Latitude	2503.7123		ddmm.mmmm
N/S Indicator	N		N=north or S=south
Longitude	12138.7446		dddmm.mmmm
E/W Indicator	E		E=east or W=west
Speed over ground	0.01	knots	True

Course over ground	34.92	degrees	
Date	270812		ddmmyy
Magnetic variation		degrees	
Variation sense			E=east or W=west (Not shown)
Mode	D		N = No position fix A = Autonomous GNSS fix D = Differential GNSS fix R = RTK fixed F = RTK float E = Estimated/Dead reckoning fix
Navigational status indicator	V		S = Safe C = Caution U = Unsafe V = Void (NMEA Ver 4.10 support only)
Checksum	*39		
<CR> <LF>			End of message termination

● VTG---Course Over Ground and Ground Speed

Table 5.1-10 contains the values for the following example:

\$GNVTG,196.90,T,,M,0.01,N,0.01,K,D*21

Table 5.1-10 VTG Data Format

Name	Example	Units	Description
Message ID	\$GNVTG		VTG protocol header
Course over ground	196.90	degrees	Measured heading
Reference	T		True
Course over ground		degrees	Measured heading
Reference	M		Magnetic
Speed over ground	0.01	knots	Measured speed
Units	N		Knots
Speed over ground	0.01	km/hr	Measured speed
Units	K		Kilometer per hour
Mode	D		N = No position fix A = Autonomous GNSS fix D = Differential GNSS fix R = RTK fixed F = RTK float

			E = Estimated/Dead reckoning fix
Checksum	*21		
<CR> <LF>			End of message termination

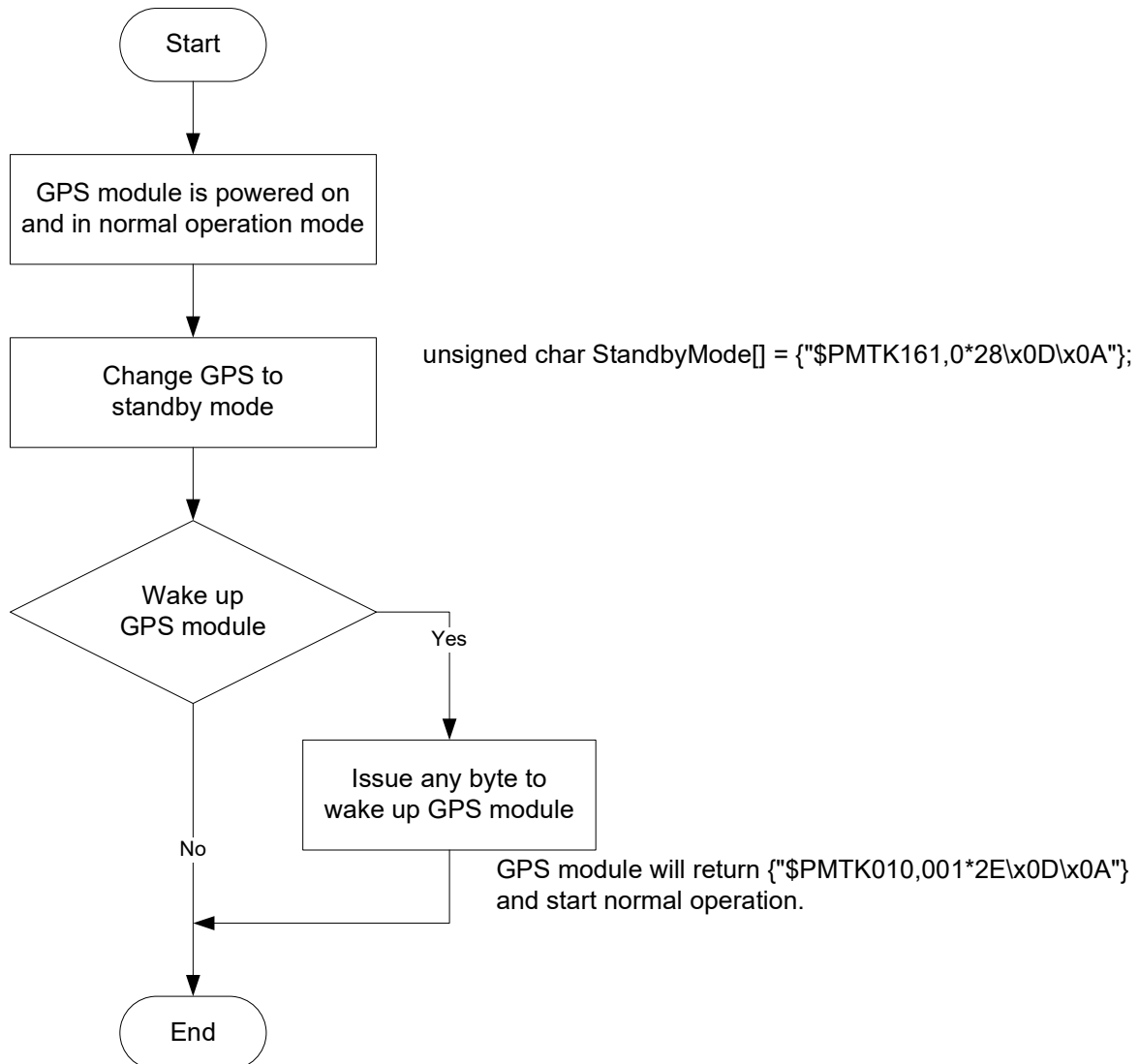
5.2 Proprietary NMEA input message

Please refer to MTK proprietary message.

5.3 Examples to configure the power mode of GNSS module

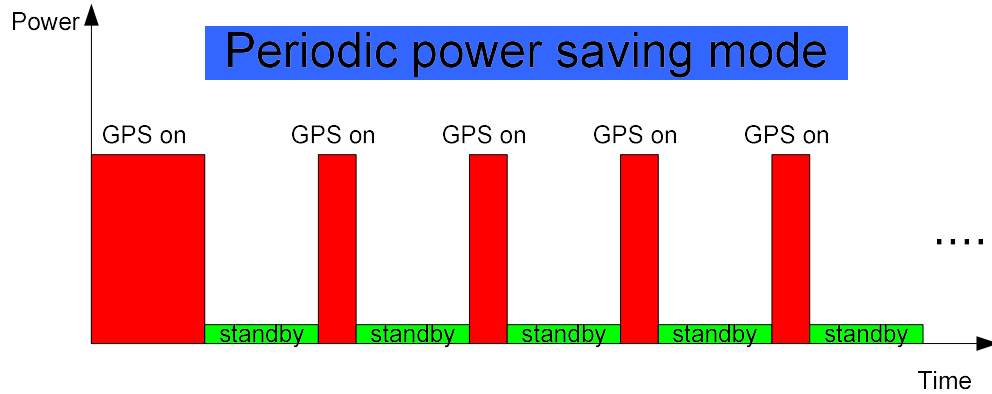
5.3.1 Standby mode

User can issue software command to make GNSS module go into standby mode that consumes less than 500uA current. GNSS module will be awaked when receiving any byte. The following flow chart is an example to make GNSS module go into standby mode and then wake up.

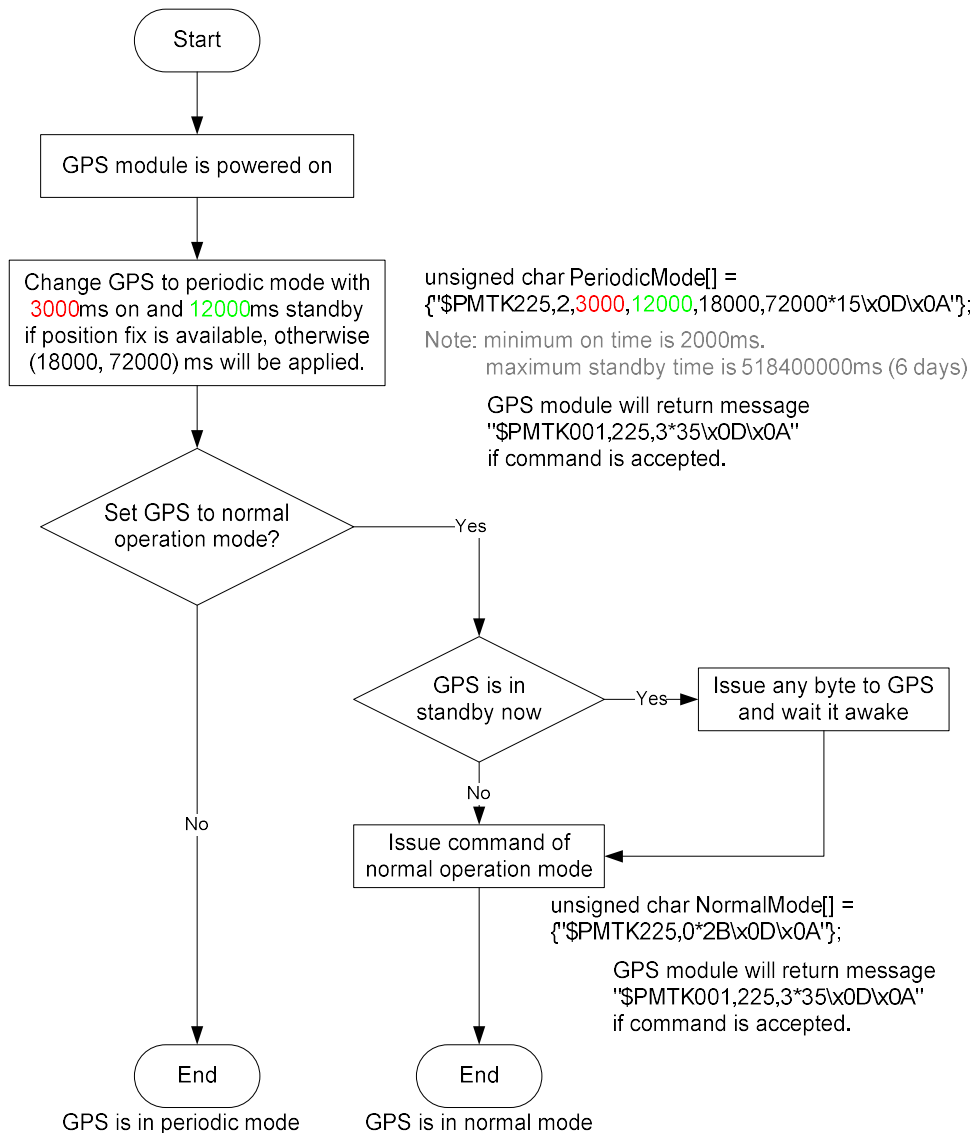


5.3.2 Periodic mode

When GNSS module is commanded to periodic mode, it will be in operation and standby periodically. Its status of power consumption is as below chart.



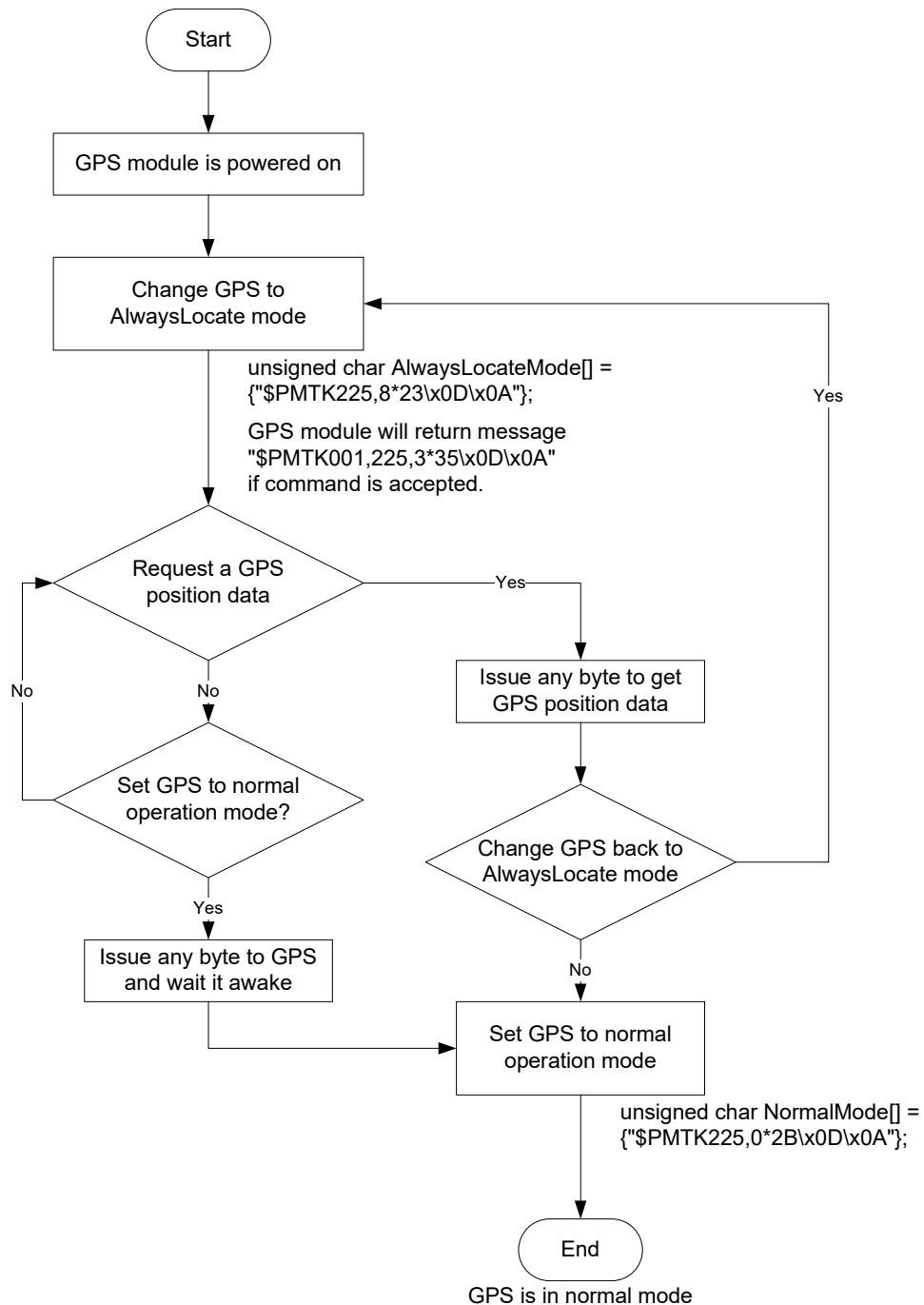
The following flow chart is an example to make GNSS module go into periodic mode and then back to normal operation mode.



5.3.3 AlwaysLocate™ mode

AlwaysLocate™ is an intelligent controller of periodic mode. Depending on the environment and motion conditions, GNSS module can adaptively adjust working/standby time to achieve balance of positioning accuracy and power consumption. In this mode, the host CPU does not need to control GNSS module until the host CPU needs the GNSS position data. The following flow chart is an example to make GNSS module go into AlwaysLocate™ mode and then back to normal operation mode.

Note: AlwaysLocate™ is a trade mark of MTK.



5.4 Data logger

The GNSS module has internal flash memory for logging GNSS data. The configurations include time interval, distance, speed, logging mode, and ... etc. For more information, please contact us.

5.5 Examples to configure the update rate of GNSS module

The GNSS module supports up to 10Hz update rate that user can configure by issuing software commands. Note that the configurations by software commands are stored in the battery-backed SRAM that is powered through VBACKUP pin. Once it drains out, the default/factory settings will be applied.

Due to the transmitting capacity per second of the current baud rate, GNSS module has to be changed to higher baud rate for high update rate of position fix. The user can use the following software commands to change baud rate.

Baud rate	Software command
Factory default	\$PMTK251,0*28<CR><LF>
4800	\$PMTK251,4800*14<CR><LF>
9600	\$PMTK251,9600*17<CR><LF>
19200	\$PMTK251,19200*22<CR><LF>
38400	\$PMTK251,38400*27<CR><LF>
57600	\$PMTK251,57600*2C<CR><LF>
115200	\$PMTK251,115200*1F<CR><LF>

Note: <CR> means Carriage Return, i.e. 0x0D in hexadecimal. <LF> means Line Feed, i.e. 0x0A in hexadecimal.

If the user does not want to change baud rate, you can reduce the output NMEA sentences by the following software commands.

NMEA sentence	Software command
Factory default	\$PMTK314,-1*04<CR><LF>
Only GLL at 1Hz	\$PMTK314,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only RMC at 1Hz	\$PMTK314,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only VTG at 1Hz	\$PMTK314,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GGA at 1Hz	\$PMTK314,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GSA at 1Hz	\$PMTK314,0,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only GSV at 1Hz	\$PMTK314,0,0,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0*29<CR><LF>
Only ZDA at 1Hz	\$PMTK314,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,1*29<CR><LF>
RMC, GGA, GSA at 1Hz and GSV at	\$PMTK314,0,1,0,1,1,5,0,0,0,0,0,0,0,0,0,0,0,0*2C<CR><LF>

0.2Hz	
If the command is correct and executed, GNSS module will output message \$PMTK001,314,3*36<CR><LF>	

After the GNSS module is changed to higher baud rate or reduced NMEA sentence, the user can configure it to high update rate of position fix by the following commands.

Interval of position fix	Software command
Every 100ms (10Hz) ⁽¹⁾	\$PMTK220,100*2F<CR><LF>
Every 200ms (5Hz)	\$PMTK220,200*2C<CR><LF>
Every 500ms (2Hz)	\$PMTK220,500*2B<CR><LF>
Every 1000ms (1Hz)	\$PMTK220,1000*1F<CR><LF>
Every 2000ms (0.5Hz) ⁽²⁾	\$PMTK220,2000*1C<CR><LF>
If the command is correct and executed, GNSS module will output message \$PMTK001,220,3*30<CR><LF>	

Note 1: The minimum interval of position fix is 100ms, i.e. the maximum update rate is 10Hz.

Note 2: The current consumption is the same with the update rate of 1Hz.

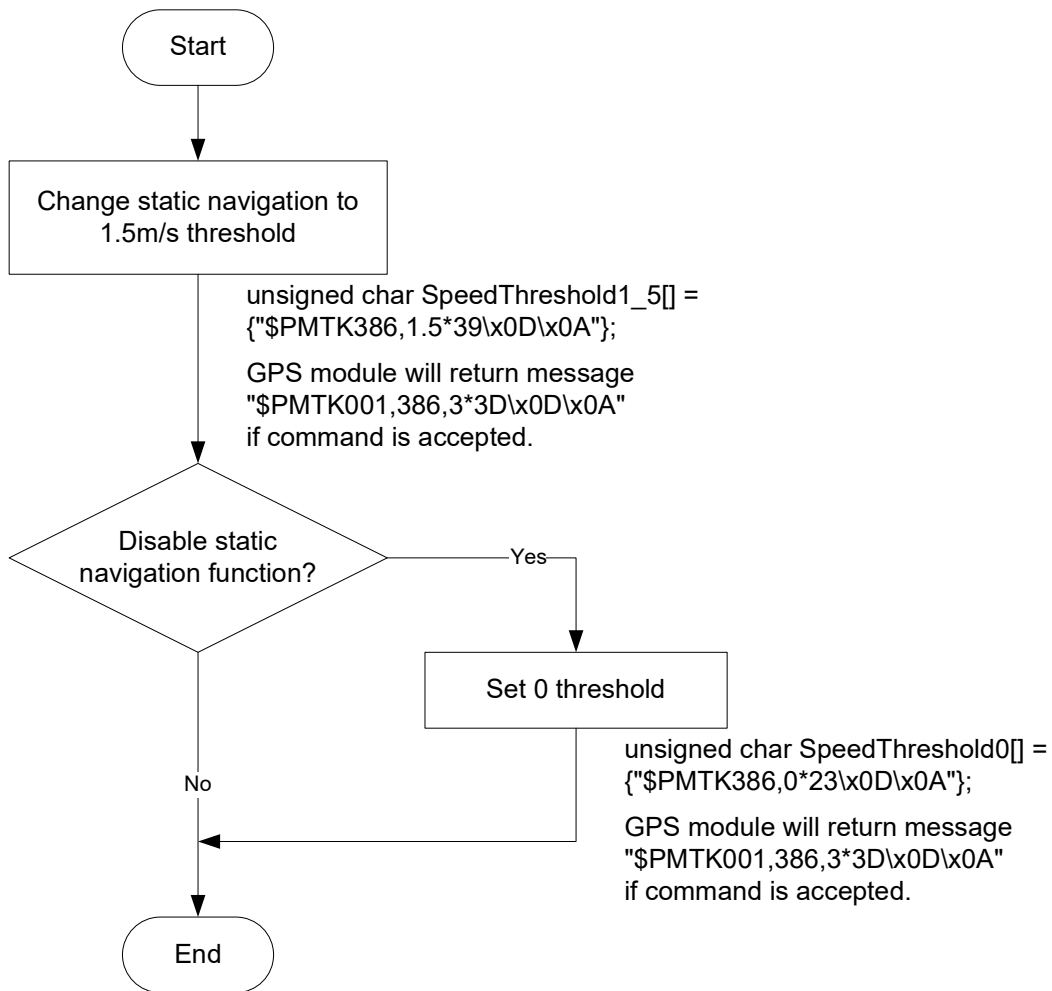
5.6 Configure the static navigation parameter

The output position of GPS module will keep the same and output speed will be zero if the actual speed is below the threshold of the static navigation parameter. This is useful for different applications. For example, the car stopped at a red light will get stationary GPS position if the threshold is 1.5m/s. It is better to disable this function by setting threshold to 0 for pedestrian navigation.

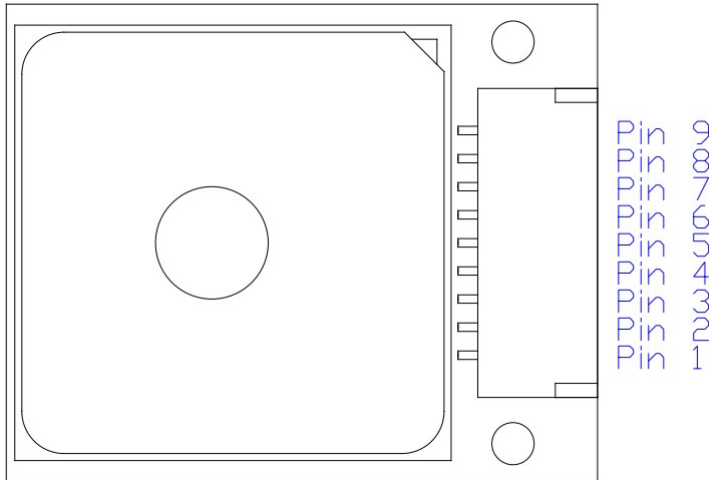
The format of the software command is as below.

\$PMTK386,speed threshold*checksum<CR><LF>

The unit of speed threshold is meter per second. The range of speed threshold is from 0.1m/s to 2.0m/s. Value 0 is to disable the function.



6 Pin assignment and descriptions



Pin #	Name	Type	Description
1	NC		Not connect.
2	1PPS	O	Pulse per second (default 100 ms pulse/sec when 3D fix is available)
3	TX	O	Serial data output
4	RX	I	Serial data input
5	NC		Not connect.
6	NC		Not connect.
7	V_BCKP	P	Backup battery supply voltage. This pin must be powered to enable the module.
8	GND	P	Ground
9	VCC	P	DC supply voltage

7 DC & Temperature characteristics

7.1 Absolute maximum ratings

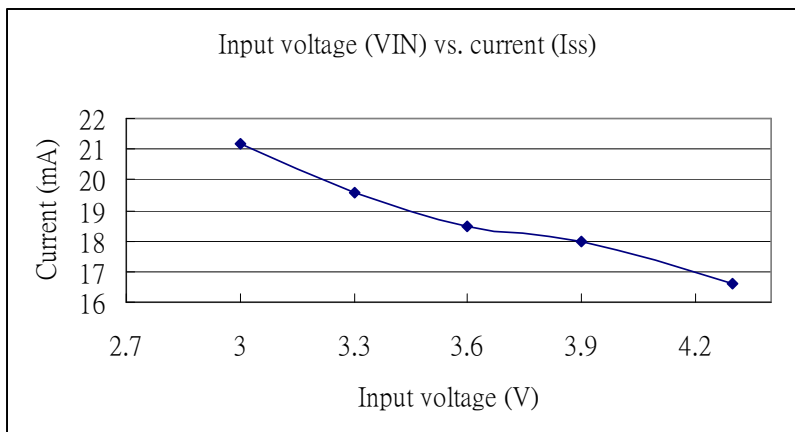
Parameter	Symbol	Ratings	Units
Input Voltage	VCC	4.3	V
Input Backup Battery Voltage	V_BCKP	4.3	V
Operating Temperature Range	Topr	-40 ~ 85	°C
Storage Temperature Range	Tstg	-40 ~ 85	°C

7.2 DC Electrical characteristics

Parameter	Symbol	Conditions	Min.	Typ.	Max.	Units
Input Voltage	VCC		3.0		4.3	V
Input Backup Battery Voltage	V_BCKP		2.0		4.3	V
Supply Current	I _{VCC}	Full operation		20 ⁽¹⁾	150 ⁽²⁾	mA
Backup Battery Current	I _{BAT}	VCC = 0		7		uA
High Level Input Voltage	V _{IH}		2.0		3.6	V
Low Level Input Voltage	V _{IL}		-0.3		0.8	V
High Level Input Current	I _{IH}		-1		1	uA
Low Level Input Current	I _{IL}		-1		1	uA
High Level Output Voltage	V _{OH}		2.4		3.3	V
Low Level Output Voltage	V _{OL}				0.4	V
High Level Output Current	I _{OH}			2		mA
Low Level Output Current	I _{OL}			2		mA

Note (1): Measured when position fix (1Hz) is available and input voltage is 3.3V. For different input voltage (VCC), the current consumption is as below chart. This is because LS2003D-G is built-in DC/DC converter.

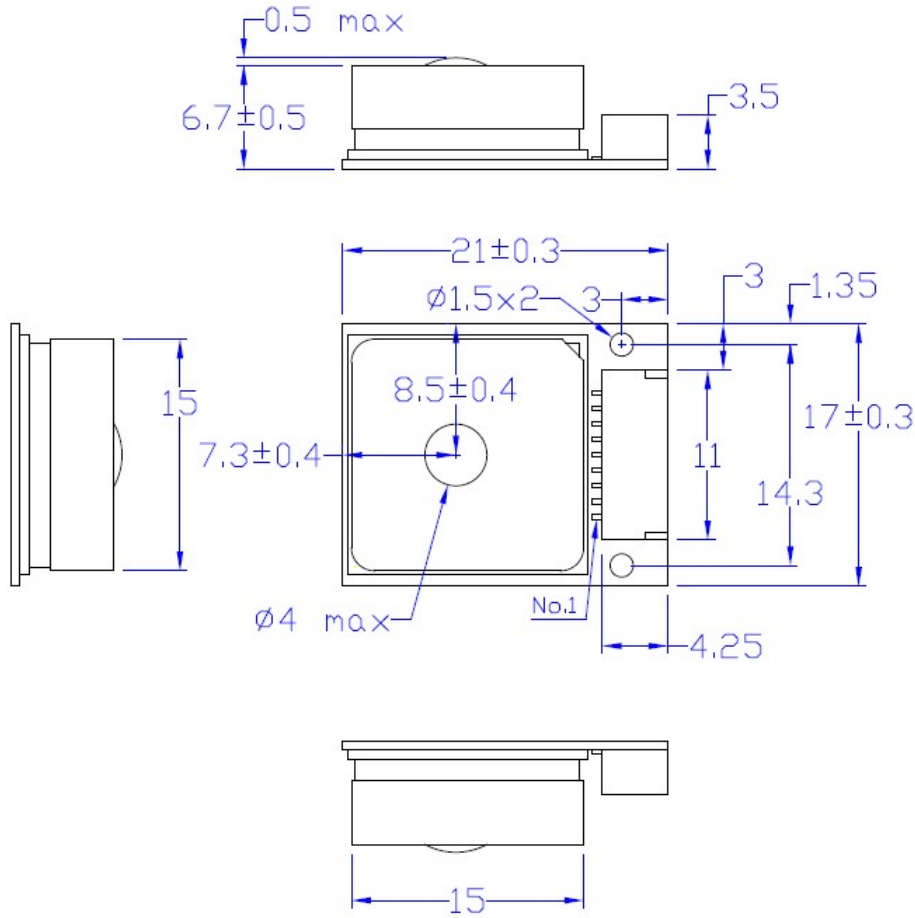
Note (2): This happens when downloading AGPS data to LS2003D-G.



7.3 Temperature characteristics

Parameter	Symbol	Min.	Typ.	Max.	Units
Operating Temperature	Topr	-40	-	85	°C
Storage Temperature	Tstg	-40	25	85	°C

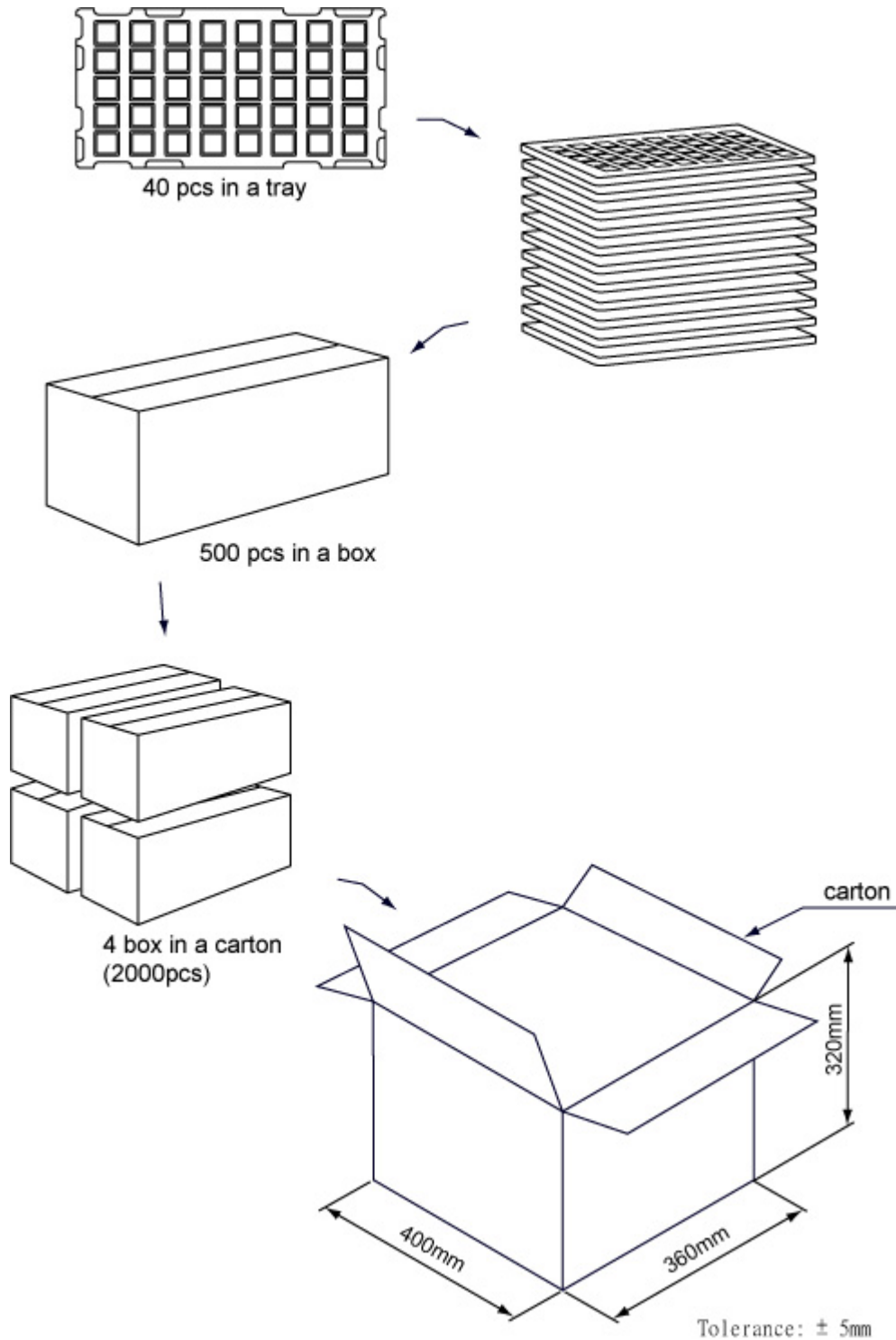
8 Mechanical specification



Unit: mm
Tolerance: ±0.2
Weight: 6.35g

The connector's part number is 1W1001WOR0-09NA from the company, TOKUTSU. It belongs to WAFER horizontal SMT single row connector, pitch 1.0mm

9 Packing information



Document change list

Revision 1.0

- First release on January 9, 2013.

Revision 1.1 (March 8, 2013)

- Changed the packing information from 1600pcs to 2000pcs in the section 9
- Added (GNGLL or GPGLL) in the table 5.1-4
- Added (GNGSA or GPGSA) in the table 5.1-5

Revision 1.2 (March 2, 2020)

- Changed the connector.
- Changed the pictures on page 1 and in section 6.
- Changed the dimension in section 8.

Revision 1.3 (April 29, 2020)

- Added “Note 1” in the section 4.1.

Revision 1.4 (July 24, 2020)

- Revised protocol support NMEA 0183 version from 4.10 to 4.00 in the section 4.
- Added “Note 2” in the section 4.
- Revised section 5.1 NMEA output message.

Revision 1.5 (November 18, 2021)

- Revised autonomous position accuracy in section 4.